Máté Tejfe

# Analysis of Distributed Systems Solutions to the Exercises

Máté Tejfel

September 19, 2013

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Lecture 1

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Theme I

Part I/a

2 Lecture 2 - Behavioral properties

3 Lecture 3 - Analysis methods

4 Lecture 4 - Classification of Petri nets

**6** Lecture 5 - Coloured Petri nets

# Agenda

Lecture 1

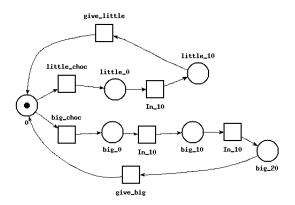
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### Exercise 1.1

### Solution A.



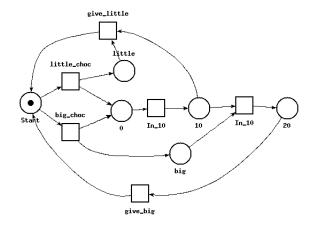
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### Solution B.

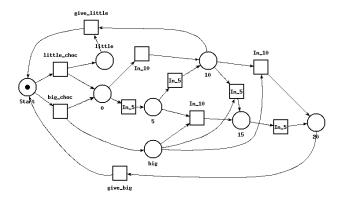


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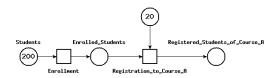
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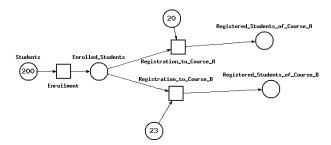
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### Exercise 1.3



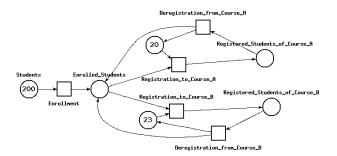


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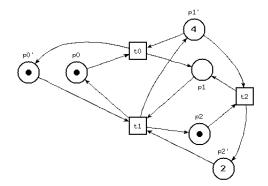
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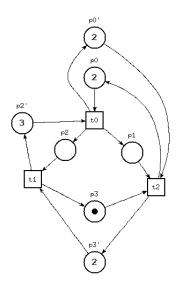
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### Exercise 1.6

Every prefix of  $t_0$ ,  $t_4$  and  $t_1$ ,  $t_3$ ,  $t_0$ ,  $t_4$ .





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### Exercise 1.9

Every prefix of  $t_0, t_1, t_2, t_3, t_0$ .

### Exercise 1.10

Every prefix of  $t_1, t_3, t_2, t_0, t_1, t_3$ .

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- 1 Lecture 1 Definition of Petri nets
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- **5** Lecture 5 Coloured Petri nets

Exercise 2.1

From A initial marking:

- $M_i$ :  $t_1, t_3, t_1, t_3, t_2, t_1, t_3$
- M<sub>i</sub>: not reachable

From *B* initial marking:

- $M_i$ :  $t_1, t_3, t_1, t_4, t_2, t_1, t_3, t_1, t_3, t_2, t_1, t_3$
- $M_i$ :  $t_1, t_3, t_2, t_1, t_4, t_1, t_3, t_2, t_1, t_1, t_3, t_3, t_1, t_1, t_2, t_2$

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### Exercise 2.2

### Reachable markings:

- {1, 0, 1, 0}
- {1, 0, 0, 1}
- {0, 0, 1, 1}
- {1, 1, 0, 0}
- {0, 1, 1, 0}
- {0, 1, 0, 1}
- {0, 0, 0, 2}
- {0, 0, 2, 0}
- {2, 0, 0, 0}

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### Exercise 2.3

Ex 2.1, A initial marking

- Boundedness : No
- Safety : No
- Liveness : t<sub>4</sub> is dead

Ex 2.1, B initial marking

- Boundedness : No
- Safety : No
- Liveness : L<sub>1</sub>

Ex 2.2

- Boundedness : Yes (k=2)
- Safety : No
- Liveness : L<sub>2</sub>

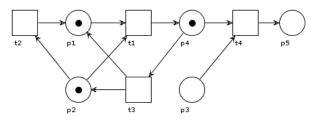
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### Exercise 2.4



The  $p_2 \Rightarrow t_1$  edge was added.

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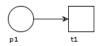
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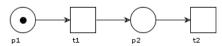
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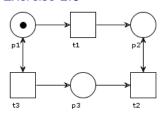


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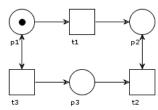
 $t_3$  is  $L_2$  but not  $L_3$ 

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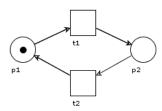
 $t_1$  is  $L_3$  but not  $L_4$ 

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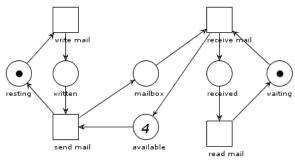
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#### Exercise 2.11

Mailbox capacity is 4.



# Agenda

- 1 Lecture 1 Definition of Petri nets
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### Exercise 3.1

Reversibility: Yes

### Home states:

- $\{p_1, p_5\}$
- $\{p_5, p_6\}$
- $\{p_2, p_3\}$
- $\{p_3, p_7\}$

It models mutual exclusion, e.g. an intersection with two traffic lights.

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- *M*<sub>1</sub> : Yes
- *M*<sub>2</sub> : Yes
- *M*<sub>3</sub> : Yes
- M<sub>4</sub> : No
- M<sub>5</sub> : No

### Exercise 3.3

#### Exercise 3.1:

- Not persistent,  $(t_1, t_2)$  is the reason.
- Persistent after reversing  $p_4$  all four edges. It is now a counter instead of a mutex!

- Not persistent, the reasons are  $(t_1, t_4)$ ,  $(t_1, t_2)$ .
- Persistent without *t*<sub>1</sub>.

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- $M_0$ :  $d_{1,2} = 1$ ,  $d_{3,2} = 1$
- $M_1$ :  $d_{1,3} = 1$ ,  $d_{2,3} = 0$
- $M_2$ :  $d_{2,3}=2$

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#### Exercise 3.5

#### Reductions:

- fusion of series places: (yellow1 + yg1 + green1) and (yellow2 + yg2 + green2)
- fusion of series transitions: (ry1 + yellow1green1 + gr1) and (ry2 + yellow2green2 + gr2)
- elimination of self-loop places: (red1) and (red2)
- fusion of series transitions: (ry1yellow1green1gr1 + safe2 + ry2yellow2green2gr2)
- elimination of self loop transitions: (ry1yellow1green1gr1safe2ry2yellow2green2gr2)



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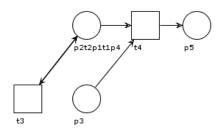
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#### Exercise 3.6

### Reductions:

- fusion of series places: (p2 + t2 + p1)
- fusion of series places: (p2t2p1 + t1 + p4)

Note: the (t3  $\Rightarrow$  p2t2p1t1p4) edge is double!

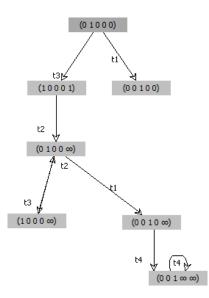


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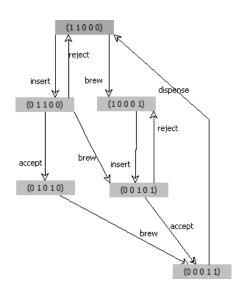


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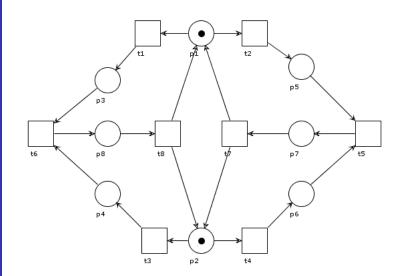
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### Exercise 3.10

Yes, because it is live and safe (k=1 bounded).

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### Exercise 4.1

Not AC (p2, p4), not live (t4) and not safe (p3)!

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# Exercise 4.2

MG, live and not safe (p3)!

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Exercise 4.3

FC, not live and safe!

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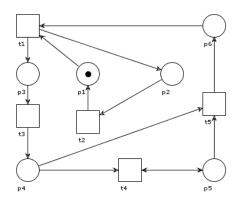
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# Exercise 4.4

### Modifications:

- $t5 \Rightarrow p4$  edge reversed
- $\bullet \ p5 \Rightarrow t4 \ edge \ added$

p4, p5 are the interesting ones!



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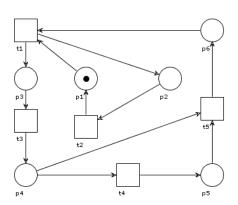
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## Exercise 4.5

### Modifications:

ullet t5  $\Rightarrow$  p4 edge reversed

p4, p5 are the interesting ones!



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- p1 is a source place
- {p2, p3} is a siphon
- $\{p4, p5\}$  is a trap
- p6 is a sink place

- $\{t2 \Rightarrow p3, t3 \Rightarrow p3\}$  is a minimal FAS
- $\{p1 \Rightarrow t2, t3 \Rightarrow p3\}$  is a minimal FAS
- $\{t2 \Rightarrow p3, p1 \Rightarrow t3\}$  is a minimal FAS
- $\{p1 \Rightarrow t2, t1 \Rightarrow t3\}$  is a minimal FAS
- p3  $\Rightarrow$  t1 is a minimum and also a minimal FAS
- $t1 \Rightarrow p1$  is a minimum and also a minimal FAS
- x set of edges is a FAS if x contains at least one of the previous 6 FAS-es

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### Exercise 4.8

It is safe, because for every reachable marking, the set of marked edges is a minimal FAS.

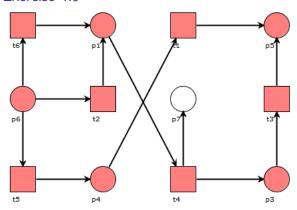
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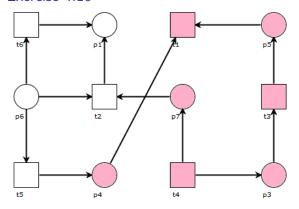
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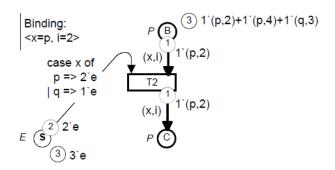
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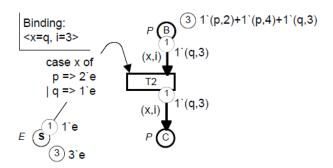
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Exercise 5.3
CPN Tools can be dowloaded from http://cpntools.org/

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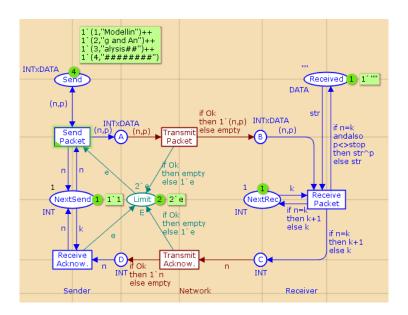
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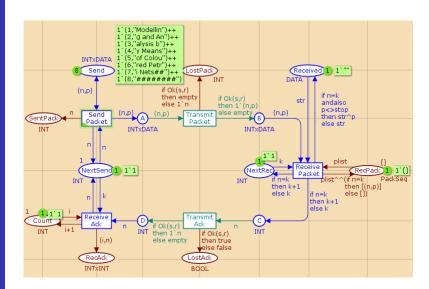
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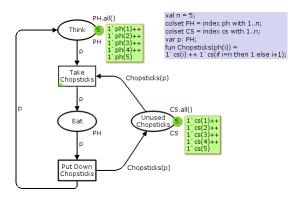


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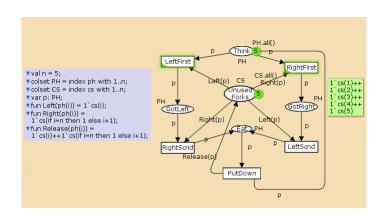
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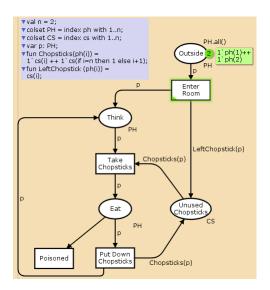
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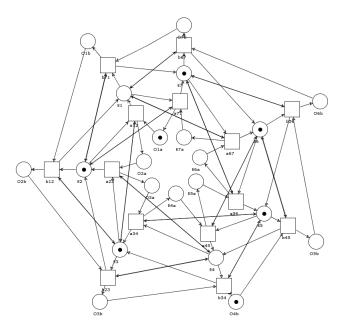
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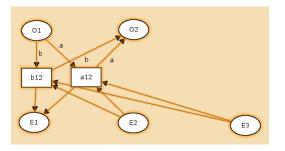


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Theme II

Part I/b

Lecture <sup>\*</sup>

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- 1 Lecture 6 Labelled Petri nets
- 2 Lecture 7 Petri Boxes
- 3 Lecture 8 Operator Boxes I.
- 4 Lecture 9 Operator Boxes II.

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## Exercise 1.1

$$\begin{split} &\Sigma_0 = (S_0, T_0, W_0, \lambda_0, M_0) \\ &S_0 = \{p_0, p_1\} \\ &T_0 = \{t_0, t_1, t_2\} \\ &W_0 = ((TS \cup ST) \times \{1\}) \cup (((S \times T) \setminus ST \cup (T \times S) \setminus TS) \times \{0\}) \\ &\lambda_0 = \{(p_0, i), (p_1, i), (t_0, rr), (t_1, br), (t_2, bb)\} \\ &M_0 = \{(p_0, 2), (p_1, 1)\} \\ &\textit{where} \\ &TS = \{(t_1, p_0), (t_0, p_1)\} \textit{ and } \\ &ST = \{(p_0, t_0), (p_0, t_1), (p_1, t_1), (p_1, t_2)\} \end{split}$$

### Exercise 1.2

The Petri net is 2-bounded, therefore not safe.

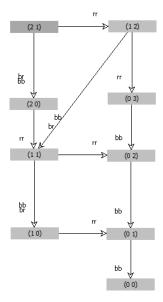
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# Exercise 1.4

Only the first three step is applicable. Two markings left on p1.

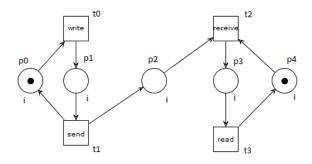
### Exercise 1.5

It is applicable. No markings left at the end.

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Exercise 1.7

The Petri net is unbounded, therefore not safe, but live.

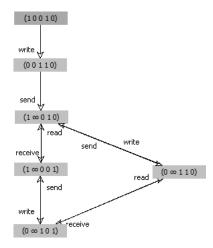
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### Lecture 6

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Exercise 1.9

$$M_0 = \{(p_1, 1), (p_4, 1)\}$$

### Exercise 1.10

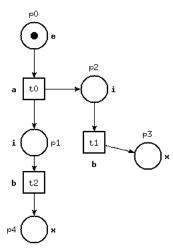
The last step is not enabled. It would require to have tokens simultaneously on p4 and p5.

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- 1 Lecture 6 Labelled Petri nets
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# Exercise 2.2

The net is ex-directed but not ex-exclusive. Marking (0,0,0,0,1,1) is reachable (applying step sequence  $\{t_0\},\{t_5\}$ ). The following transitions are independent of transition  $t_0$ :  $t_3,t_6$ .

### Exercise 2.3

The ex-asymmetric transitions of the net are the following:  $t_0$ :  $t_1$ .

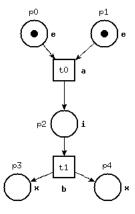
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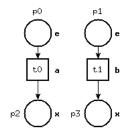
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## Exercise 2.5



### Exercise 2.6

The net is a Petri box, but the marking (0, 1, 1, 1) (which is not clean) is reachable from  $M_{\bullet \Sigma}$ , namely, it is not a static box.

# Exercise 2.7

The net is a Petri box, but the marking (0,0,0,2) (which is not safe) is reachable from  $M_{\bullet \Sigma}$ , namely, it is not a dynamic box.

# Exercise 2.8

Marking (0,1,0,1) is reachable from the initial marking (applying step  $\{t_1\}$ ), so the net is not ex-exclusive.

## Exercise 2.9

The net is an entry box, since it is a Petri box, and every marking reachable from  $M_{\bullet \Sigma}$  and  $M_{\Sigma^{\bullet}}$  is safe and clean.

### Exercise 2.10

Transitions  $t_1$ ,  $t_2$  are independent. Marking (0,1,0,0,1) is reachable from the initial marking (applying step sequence  $\{t_0\}, \{t_2\}$ ), so the net is not ex-exclusive.

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- 4 Lecture 9 Operator Boxes II.

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#### Exercise 3.1

Yes. The following execution is enabled.

$$\begin{array}{ll} (\{p_0,p_1\},\emptyset) & [\{t_0,t_3\}> & (\{p_2,p_3\},\emptyset) & [\{t_4\}:\{t_1\}^+> \\ (\{p_1\},\{t_1\}) & [\{t_3\}:\{t_1\}^-> & (\{p_0,p_3\},\emptyset). \end{array}$$

#### Exercise 3.2

Yes. The following execution is enabled.

$$(\{p_0, p_1\}, \emptyset)$$
  $[\{t_0, t_3\} > (\{p_2, p_3\}, \emptyset)$   $[\{t_2\} : \{t_5\}^+ > (\{p_4, p_5\}, \{t_5\}).$ 

#### Exercise 3.3

The following complex markings are directly reachable from  $\mathcal{M}''=(\{p_0\},\{t_5\}).$ 

$$(\{p_0,p_5\},\emptyset);\;(\{p_2,p_5\},\emptyset);\;(\{p_2\},\{t_5\});\;(\{p_5\},\{t_0\});(\emptyset,\{t_0,t_5\})$$

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No. Execution

 $(\{p_0\},\emptyset)$   $[\{t_2\}>$   $(\{p_2,p_3\},\emptyset)$   $[\{t_3\}:\{t_0\}^+>$   $(\{p_5\},\{t_0\})$  is enabled. However  $t_1$  is not enabled in  $(\{p_5\},\{t_0\})$ .

### Exercise 3.5

Yes. The following execution is enabled.

$$(\{p_0\},\emptyset)$$
  $[\{t_2\}>$   $(\{p_2,p_3\},\emptyset)$   $[\{t_0\}:\{t_3\}^+>$   $(\{p_4\},\{t_3\})$   $[\{t_1\}^+:\{t_3\}^->$   $(\{p_5\},\{t_1\}).$ 

### Exercise 3.6

Yes. The following execution is enabled.  $(\{p_0, p_1\}, \emptyset)$   $[\{t_0\} > (\{p_2, p_3\}, \emptyset)$   $[\{t_3\} : \{t_1\}^+ > (\{p_4\}, \{t_1\})$   $[\{t_2\}^+ : \{t_1\}^- > (\{p_2\}, \{t_2\}).$ 

### Exercise 3.7

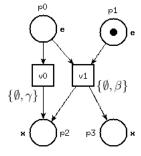
Yes. The following execution is enabled.  $(\{p_0, p_1\}, \emptyset)$   $[\{t_0\} > (\{p_2, p_3\}, \emptyset)$   $[\{t_3\} : \{t_1\}^+ > (\{p_4\}, \{t_1\})$   $[\{t_2\}^+ > (\emptyset, \{t_1, t_2\}).$ 

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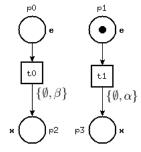


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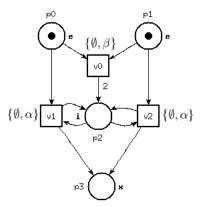


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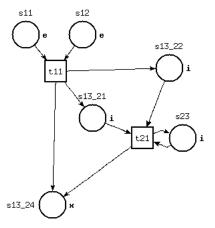


- 1 Lecture 6 Labelled Petri nets
- 2 Lecture 7 Petri Boxes
- 3 Lecture 8 Operator Boxes I.
- 4 Lecture 9 Operator Boxes II.

Lecture 6

Lecture

Lecture 9

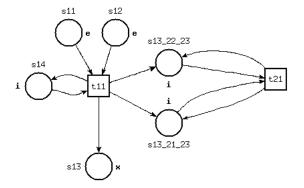


Lecture 6

Lecture 7

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Lecture 9

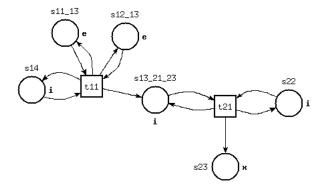


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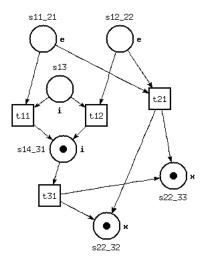


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#### Analysis of Distributed Systems

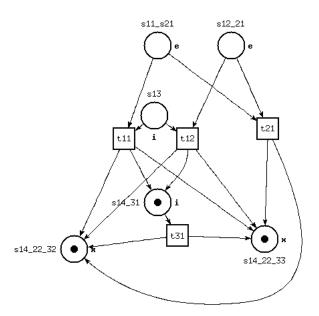
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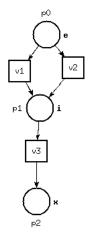
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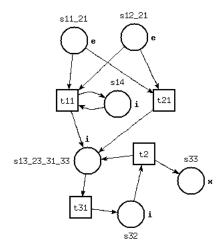


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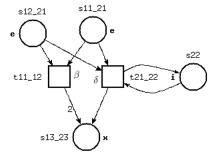


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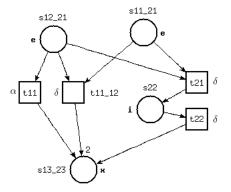


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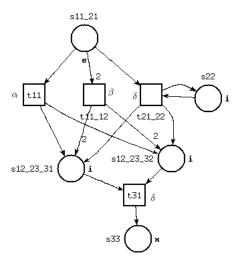


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#### Analysis of Distributed Systems

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Lecture 10 Labelled Transition Systems

Lecture 1

Lecture 1

Lecture 13

Lecture 14

Theme III

Part II

- 1 Lecture 10 Labelled Transition Systems
- 2 Lecture 11 Communicating Sequential Processes
- 3 Lecture 12 Axiomatic Semantics of CSP
- 4 Lecture 13 Denotational Semantics of CSP
- **5** Lecture 14 Communication in CSP

Lecture 10 -Labelled Transition Systems

Lecture 1

Lecture 13

#### Exercise 1.1

$$p = a(bnil + cnil)$$

### Exercise 1.2

$$p = a(bnil + cq), q = dp$$

### Exercise 1.3

$$\begin{array}{l} \textit{a(bnil} + \textit{c(dnil} + \textit{bdnil)}) \mid\mid \textit{acbnil} \\ \stackrel{\textit{a}}{\rightarrow} \; \textit{bnil} + \textit{c(dnil} + \textit{bdnil}) \mid\mid \textit{cbnil} \\ \stackrel{\textit{c}}{\rightarrow} \; \textit{dnil} + \textit{bdnil} \mid\mid \textit{bnil} \\ \stackrel{\textit{b}}{\rightarrow} \; \textit{dnil} \mid\mid \textit{nil} \\ \not \rightarrow \end{array}$$

Consequently the process corresponds to the environment.

#### Lecture 10 -Labelled Transition Systems

#### Exercise 1.4

```
- abdnil + a(dnil + cnil) || a(bnil + cnil)
   \stackrel{a}{\rightarrow} dnil + cnil || bnil + cnil
   \stackrel{c}{\rightarrow} nil || nil
   \rightarrow
```

- 
$$abdnil + a(dnil + cnil) || a(bnil + cnil)$$
  
 $\stackrel{a}{\rightarrow} bdnil || bnil + cnil$   
 $\stackrel{b}{\rightarrow} dnil || nil$   
 $\stackrel{}{\rightarrow}$ 

Consequently the process corresponds to the environment.

Lecture 1

### Exercise 1.5

- $abnil + adnil \mid\mid abnil + adnil \xrightarrow{a} dnil \mid\mid dnil$ 
  - $\stackrel{d}{\rightarrow}$  nil || nil  $\stackrel{/}{\rightarrow}$

Consequently the process does not correspond to the environment.

Locturo 1

#### Exercise 1.6

nil, a(bnil + dnil), anil + cnil, a(bnil + dnil + cnil), ...

### Exercise 1.7

$$\tau(\textit{a(bnil} + \textit{c(dnil} + \textit{bdnil)}) = \{\textit{ab}, \; \textit{acd}, \; \textit{acbd}\}$$

### Exercise 1.8

$$\tau'(a(bnil+c(dnil+bdnil)) = \{\epsilon, a, ab, ac, acd, acb, acbd\}$$

$$abnil + a(cnil + dnil)$$

$$\stackrel{A5}{=} a(bnil + (cnil + dnil))$$

$$\stackrel{A1}{=} a((bnil + cnil) + dnil)$$

$$\stackrel{A5}{=}$$
  $a(bnil + cnil) + adnil$ 

Lecture 13

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$$a((bcnil + dnil) + d(cnil + nil))$$

$$\stackrel{A4}{=} a((bcnil + dnil) + dcnil)$$

$$\stackrel{A5}{=} a(bcnil + dnil) + adcnil$$

$$\stackrel{A5}{=} (abcnil + adnil) + adcnil$$

$$\stackrel{A1}{=} abcnil + (adnil + adcnil)$$

$$\stackrel{A4}{=} ab(cnil + nil) + (adnil + adcnil)$$

$$\stackrel{A5}{=} ab(cnil + nil) + a(dnil + dcnil)$$

$$\stackrel{A5}{=} ab(cnil + nil) + a(d(nil + cnil))$$

Lecture 1

- 1 Lecture 10 Labelled Transition Systems
- 2 Lecture 11 Communicating Sequential Processes
- 3 Lecture 12 Axiomatic Semantics of CSP
- 4 Lecture 13 Denotational Semantics of CSP
- **5** Lecture 14 Communication in CSP

Lecture 10 Labelled Transition Systems

Lecture 11

Lecture 13

Lecture 14

#### Exercise 2.1

$$CSP = 10 \rightarrow CS10$$
,  $CS10 = (5 \rightarrow CS15 \mid little\_choc \rightarrow CS)$   $CS15 = big\_choc \rightarrow CS$ , where  $\alpha CSP = \{5, 10, little\_choc, big\_choc\}$ 

$$M = (a \rightarrow M_1 \mid b \rightarrow M_2 \mid c \rightarrow M_3)$$

$$M_1 = (b \rightarrow M_2 \mid c \rightarrow M_3 \mid d \rightarrow M)$$

$$M_2 = c \rightarrow M_3$$

$$M_3 = d \rightarrow M$$
where  $\alpha M = \{a, b, c, d\}$ 

#### Analysis of Distributed Systems

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Lecture 10 -Labelled Transition Systems

Lecture 11

Lecture 1.

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# Exercise 2.3

 $P = AD_0$ ,  $AD_0 = prod1 \rightarrow BD_1$ ,

 $BD_i = (prod2 \rightarrow AD_i \mid cons1 \rightarrow BC_{i-1})$ , where  $i \in \mathbb{N}$ ,  $BC_i = (cons2 \rightarrow BD_i \mid prod2 \rightarrow AC_i)$ , where  $i \in \mathbb{N}_{\not\vdash}$ ,

 $AC_i = (cons2 \rightarrow AD_i \mid prod1 \rightarrow AC_{i+1})$ , where  $i \in \mathbb{N}_{\not\vdash}$ ,  $AD_i = (prod1 \rightarrow AD_{i+1} \mid cons1 \rightarrow AC_{i-1})$ , where  $i \in \mathbb{N}$ ,  $BD_0 = prod2 \rightarrow AD_0$ .

 $\alpha P = \{ prod1, prod2, cons1, cons2 \}$ 

### Exercise 2.4

 $P = null \rightarrow A_0$ ,

 $A_i = (a \rightarrow A_{i+1} \mid null \rightarrow B_{i,0}),$ where  $i \in \mathbb{N}_0,$ 

 $B_{i,j} = (b \rightarrow B_{i-1,j+1} \mid null \rightarrow C_{j,0}),$ where  $i \in \mathbb{N}, j \in \mathbb{N}_0, (i > 0),$  $B_{0,i} = null \rightarrow C_i),$  where  $j \in \mathbb{N}_0,$ 

 $\mathcal{L}_{0,j} = null \to \mathcal{L}_{j}$ ), where  $j \in \mathbb{N}_{0}$ ,  $\mathcal{L}_{j} = (c \to \mathcal{L}_{j-1} \mid null \to STOP)$ , where  $j \in \mathbb{N}$ , (j > 0),  $\mathcal{L}_{0} = null \to STOP$ .

and  $\alpha P = \{null, a, b, c\}$ 

Lecture 1

Lecture 14

#### Exercise 2.5

 $\begin{array}{l} P \mid\mid Q \text{, where} \\ P = b1 \rightarrow \textit{ meetB} \rightarrow \textit{meetE} \rightarrow e1 \rightarrow P \text{,} \\ \alpha P = \{b1, \textit{meetB}, \textit{meetE}, e1\}, \\ Q = b2 \rightarrow \textit{meetB} \rightarrow \textit{meetE} \rightarrow e2 \rightarrow Q, \\ \alpha Q = \{b2, \textit{meetB}, \textit{meetE}, e2\}, \end{array}$ 

$$\begin{array}{l} (P \mid\mid Q) \mid\mid R \text{, where} \\ P = b3 \rightarrow \mod 2 \rightarrow \mod 3 \rightarrow P, \\ \alpha P = \{b3, meet2, meet3\}, \\ Q = b1 \rightarrow \mod 1B \rightarrow \mod 2 \rightarrow \mod 1E \rightarrow \mod 3 \rightarrow Q, \\ \alpha Q = \{b1, meet\_1B, meet\_1E, meet2, meet3\}, \\ R = b2 \rightarrow \mod 1B \rightarrow \mod 2 \rightarrow \mod 1E, \\ \alpha R = \{b2, meet\_1B, meet\_1E, meet2\}. \end{array}$$

Lecture 12

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#### Exercise 2.7

$$P = (a \rightarrow (b \rightarrow STOP \mid c \rightarrow STOP) \mid b \rightarrow d \rightarrow STOP),$$
  
 $\alpha P = \{a, b, c, d\}$ 

$$P = (a \rightarrow (b \rightarrow STOP \mid c \rightarrow STOP) \mid d \rightarrow STOP \mid b \rightarrow (c \rightarrow STOP \sqcap c \rightarrow d \rightarrow STOP)), \alpha P = \{a, b, c, d\}$$

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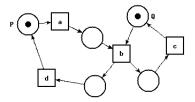
Lecture 10 Labelled Transition Systems

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### Exercise 2.9



Exercise 2.10 acbdnil + cabdnil

# Agenda

- 1 Lecture 10 Labelled Transition Systems
- 2 Lecture 11 Communicating Sequential Processes
- 3 Lecture 12 Axiomatic Semantics of CSP
- 4 Lecture 13 Denotational Semantics of CSP
- **6** Lecture 14 Communication in CSP

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Lecture 13

#### Exercise 3.1

$$P \parallel Q = (a \rightarrow c \rightarrow b \rightarrow (P \parallel Q) \mid c \rightarrow a \rightarrow b \rightarrow (P \parallel Q))$$

### Exercise 3.2

$$P \mid\mid Q = b \rightarrow (a \rightarrow c \rightarrow (P \mid\mid Q) \mid c \rightarrow a \rightarrow (P \mid\mid Q))$$

$$P \mid\mid Q = a \rightarrow R$$
, where  $R = b \rightarrow (a \rightarrow c \rightarrow R \mid c \rightarrow a \rightarrow R)$ 

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#### Exercise 3.4

$$P \mid\mid Q = a \rightarrow b \rightarrow (P \mid\mid Q)$$

### Exercise 3.5

$$P \mid\mid Q = x \rightarrow y \rightarrow (w \rightarrow z \rightarrow y \rightarrow (P \mid\mid Q) \\ \mid z \rightarrow w \rightarrow y \rightarrow (P \mid\mid Q))$$

### Exercise 3.6

$$P \mid\mid Q = (a \rightarrow STOP) \sqcap (a \rightarrow b \rightarrow (P \mid\mid Q))$$

$$P \setminus \{b\} = (a \rightarrow P \mid d \rightarrow c \rightarrow P)$$
, where  $\alpha P = \{a, c, d\}$ 

Lecture :

#### Exercise 3.8

$$P \mid\mid Q = (a \rightarrow b \rightarrow c \rightarrow (P \mid\mid Q)) \sqcap (a \rightarrow c \rightarrow d \rightarrow (P \mid\mid Q))$$

#### Exercise 3.9

$$P \mid\mid Q = e \rightarrow R$$
, where  $R = a \rightarrow (b \rightarrow e \rightarrow W \mid e \rightarrow b \rightarrow W)$ , where  $W = c \rightarrow (d \rightarrow e \rightarrow R \mid e \rightarrow d \rightarrow R)$ 

$$P \parallel Q = (x \rightarrow y \rightarrow z \rightarrow (P \parallel Q)) \sqcap (x \rightarrow z \rightarrow w \rightarrow (P \parallel Q))$$

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Lecture 10 Labelled Transition Systems

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Lecture 1

#### Exercise 4.1

- 1.  $traces(R(a)) = \{ <>, < b >, < b, c > \}$
- 2.  $traces(R(b)) = \{ <>, < d > \}$
- $\Rightarrow traces(W)$ = {<>, < a >, < a, b >, < a, b, c >, < b >, < b, d >}

- 1.  $traces(P) = \{ <>, < b >, < b, c > \}$
- 2.  $traces(Q) = \{ <>, < d >, < d, c > \}$
- $\Rightarrow traces(P \sqcap Q)$   $= \{ <>, < b>, < b, c>, < d>, < d, c> \}$

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Lecture 1

#### Exercise 4.3

- 1.  $traces(R) = \{ <>, < d >, < d, c > \}$
- 2.  $traces(W) = \{ <>, < b >, < b, d >, < b, d, c > \}$
- $\Rightarrow traces(R \square W)$   $= \{ \langle >, < d >, < d, c >, < b >, < b, d >, < b, d, c > \}$

#### Exercise 4.4

•  $traces((P \sqcap Q) || (R \square W))$ =  $traces(P \sqcap Q) \cap traces(R \square W)$ =  $\{<>, < b>, < d>, < d, c>\}$  Labelled Transition Systems

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#### Exercise 4.5

- Here  $F(X) = coin \rightarrow choc \rightarrow X$ .
- According to the 3. item of definition of function traces it is enough to see:

 $\forall n \in \mathbb{N} : traces(F^n(STOP)) = \{s \mid s \leq < coin, choc > ^n\}.$  Using induction:

```
 \begin{array}{l} \mathsf{n=0} \;\; traces(F^0(STOP)) = traces(STOP) = \{<>\} \\ &= \{s \mid s \leq < coin, choc >^0\}, \\ \mathsf{n=k+1} \;\; traces(F^{k+1}(STOP_A)) \\ &= traces(F(F^k(STOP_A))) \\ &= traces(coin \to choc \to F^k(STOP)) \\ &= \{<>, < coin >\} \\ &\quad \cup \{< coin, choc >^{\wedge} t \mid t \in traces(F^k(STOP)))\} \\ &= \{<>, < coin >\} \\ &\quad \cup \{< coin, choc >^{\wedge} t \mid t \leq < coin, choc >^{n} )\} \\ &= \{t \mid t \leq < coin, choc >^{n+1}\} \end{array}
```

Lecture 13

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### Exercise 4.6

- $traces(P) = \{ <>, < a >, < a, b >, < a, c > \},$
- $\forall t \in traces(P) : (t \downarrow a) \geq (t \downarrow c)$ ,
- $\Rightarrow$  P sat  $((tr \downarrow a) \geq (tr \downarrow c))$ .

### Exercise 4.7

- $P \mid\mid Q = a \rightarrow b \rightarrow c \rightarrow STOP$ ,
- $traces(P || Q) = \{<>, < a>, < a, b>, < a, b, c>\},$
- $\forall t \in traces(P \mid\mid Q) : ((t \downarrow a) \leq (t \downarrow b)),$
- $\Rightarrow$   $(P \mid\mid Q)$  sat  $((tr \downarrow a) \leq (tr \downarrow b))$ .

- $traces(P \sqcap Q) = \{<>, < b>, < b, c>, < a>, < a, b>\},$
- $\forall t \in traces(P \sqcap Q) : ((t \downarrow a) + (t \downarrow c) \leq 1)$ ,
- $\Rightarrow$   $(P \sqcap Q)$  sat  $((tr \downarrow a) + (tr \downarrow c) \leq 1)$ .

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Analysis of
Distributed
Systems
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Lecture 10 Labelled Transition Systems

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# Exercise 4.9

Let be  $MySpec = ((tr \downarrow a) \leq 1 + (tr \downarrow b) + (tr \downarrow d)).$ 

- 1.  $(tr = <>) \Rightarrow MySpec$
- $\Rightarrow$  STOP sat  $(tr = <>) \Longrightarrow$  STOP sat MySpec
  - 2. Suppose X sat MySpec

$$traces(F(X)) = \{ <>, < a >, < a, b >, < a, c > \}$$
  
 $\cup \{ < a, b, c >^{\land} t \mid t \in traces(X) \}$ 

- $\cup \{\langle a, c, d \rangle^{\wedge} \mid t \in traces(X)\}$
- 2.a  $(<>\downarrow a) = 0, (<>\downarrow b) + (<>\downarrow d) = 0,$ 
  - $(\langle a \rangle \downarrow a) = 1, (\langle a \rangle \downarrow b) + (\langle a \rangle \downarrow d) = 0,$
  - $(\langle a, b > \downarrow a \rangle = 1, (\langle a, b > \downarrow b) + (\langle a, b > \downarrow d) = 1, (\langle a, c > \downarrow a \rangle = 1, (\langle a, c > \downarrow b) + (\langle a, c > \downarrow d) = 0.$
- $(\langle a, c \rangle \downarrow a) = 1, (\langle a, c \rangle \downarrow b) + ($ 
  - $(\langle a, b, c \rangle^{\wedge} t \downarrow b) = (t \downarrow b) + 1,$  $(\langle a, b, c \rangle^{\wedge} t \downarrow d) = (t \downarrow d),$
  - so  $((\langle a,b,c\rangle^{\wedge}t\downarrow a)=((\langle a,b,c\rangle^{\wedge}t\downarrow a))$

$$\leq 1 + (\langle a, b, c \rangle^{\wedge} t \downarrow b) + (\langle a, b, c \rangle^{\wedge} t \downarrow d))$$

equivalent with  $((t \downarrow a) \le 1 + (t \downarrow b) + (t \downarrow d))$  (which will hold because of the assumption).

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2.c  $(\langle a,c,d \rangle^{\wedge} t\downarrow a) = (t\downarrow a)+1$ ,  $(\langle a,c,d \rangle^{\wedge} t\downarrow b) = (t\downarrow b)$ ,  $(\langle a,c,d \rangle^{\wedge} t\downarrow d) = (t\downarrow d)+1$ , so  $((\langle a,c,d \rangle^{\wedge} t\downarrow a)$   $\leq 1+(\langle a,c,d \rangle^{\wedge} t\downarrow b)+(\langle a,c,d \rangle^{\wedge} t\downarrow d))$  equivalent with  $((t\downarrow a)\leq 1+(t\downarrow b)+(t\downarrow d))$  (which will hold because of the assumption).

- $(2.a) \land (2.b) \land (2.c) \Rightarrow F(X)$  sat MySpec.
- $(1.) \land (2.) \Rightarrow P$  sat MySpec.

. .

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Lecture 13

Lecture 1

1. 
$$P$$
 sat  $(0 \leq ((tr \downarrow a) - (tr \downarrow b)) \leq 1)$ 

2. 
$$Q$$
 sat  $(0 \le ((tr \downarrow b) - (tr \downarrow c)) \le 1)$ 

$$\Rightarrow P \mid\mid Q$$

$$sat \left( (0 \leq (((tr \uparrow \alpha P) \downarrow a) - ((tr \uparrow \alpha P) \downarrow b)) \leq 1) \right)$$

$$\land (0 \leq (((tr \uparrow \alpha Q) \downarrow b) - ((tr \uparrow \alpha Q) \downarrow c)) \leq 1)$$

$$\Rightarrow P \parallel Q$$

$$sat \left( (0 \leq ((tr \downarrow a) - (tr \downarrow b)) \leq 1 \right)$$

$$\land (0 \leq ((tr \downarrow b) - (tr \downarrow c)) \leq 1) \right)$$

$$\Rightarrow$$
  $P \mid\mid Q \ sat \ (0 \leq ((tr \downarrow a) - (tr \downarrow c)) \leq 2)$ 

Lactura 1

Lecture 14

# Agenda

- 1 Lecture 10 Labelled Transition Systems
- 2 Lecture 11 Communicating Sequential Processes
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- **5** Lecture 14 Communication in CSP

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Lecture 10 Labelled Transition Systems

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#### Exercise 5.1

$$P||Q = c1?x \to c2.(x+5) \to c3!(2*x+10) \to STOP$$

Exercise 5.2

$$(P||Q) \setminus \{c2\} = c1?x \to c3!(2*x+10) \to STOP$$

Exercise 5.3

$$P||Q_{10} = in?x \to c1.x \to c2.(10*x) \to out!(10*x) \to (P||Q_{10})$$

Exercise 5.4

$$(P||Q_5)\setminus\{c1,c2\}=in?x\rightarrow out!(5*x)\rightarrow ((P||Q_5)\setminus\{c1,c2\})$$

$$(P||Q) = (in1?x \rightarrow in2?y \rightarrow c1.x \rightarrow c2.(x+y) \rightarrow out!(x+y) \rightarrow (P||Q) |in2?y \rightarrow in1?x \rightarrow c1.x \rightarrow c2.(x+y) \rightarrow out!(x+y) \rightarrow (P||Q))$$

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#### Exercise 5.6

$$\begin{aligned} (P||Q) &= \\ & \textit{in1?x} \rightarrow \textit{c1.x} \\ &\rightarrow (\textit{in2?y} \rightarrow \textit{out!x} \rightarrow \textit{c2.(x*y)} \rightarrow \textit{out!(x*y)} \rightarrow (P||Q) \\ &\mid \textit{out!x} \rightarrow \textit{in2?y} \rightarrow \textit{c2.(x*y)} \rightarrow \textit{out!(x*y)} \rightarrow (P||Q)) \end{aligned}$$

#### Exercise 5.7

$$Q = (in?y \rightarrow out!(y_1 * y_2 + 5) \rightarrow Q)$$

Exercise 5.8

$$Q = (in?y \rightarrow out!(y_1, (y_1 * y_2 + 3)) \rightarrow Q)$$

Exercise 5.9

$$Q = (in?y \to out!(y_1, (y_2 + (y_1 * y_3)), (y_1 * y_3)) \to Q)$$

$$Q_i = (in?y \rightarrow out!(y_1, (y_2 + \frac{y_1}{i} * y_3), \frac{y_1}{i} * y_3) \rightarrow Q_i)$$