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## 5. Complexity of Query Evaluation

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## Outline

5. Complexity of Query Evaluation
5.1 Measures of Complexity
5.2 Complexity of First-order Queries
5.3 Complexity of Conjunctive Queries
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## Beyond Traktenbrot's Theorem

■ By Traktenbrot's Theorem, it is undecidable to check whether a given first-order query $Q$ produces some output over some database.
■ What happens if $D$ is actually given as input?

The following are natural (decision) problems in this context:

## QUERY-OUTPUT-TUPLE (QOT)

INSTANCE: A database $D$, a query $Q$, a tuple $\vec{c}$ of values. QUESTION: Is it true that $\vec{c} \in Q(D)$ ?

## BOOLEAN-QUERY-EVALUATION (BQE)

INSTANCE: A database $D$, a Boolean query $Q$.
QUESTION: Does $Q$ evaluate to true in $D$ ?
NOTE: we often view Boolean domain calculus queries $\{\rangle| \phi\}$ simply as closed formulae $\phi$.

## QUERY-NON-EMPTINESS (QNE)

INSTANCE: A database $D$, a query $Q$.
QUESTION: Does query $Q$ yield a non-empty result over the $D B D$, i.e. $Q(D) \neq \emptyset$ ?

## QOT vs. BQE vs. QNE

We concentrate next on the complexity of BQE.
Not a limitation: in our setting QOT and QNE are essentially the same problems as BQE:

## From QOT to BQE

Assume a database $D$, a domain calculus query $Q=\{\vec{x} \mid \phi(\vec{x})\}$, and a value tuple $\vec{c}=\left\langle c_{1}, \ldots, c_{n}\right\rangle$. Then $\vec{c} \in Q(D)$ iff $Q^{\prime}$ evaluates to true in $D$, where

$$
\begin{gathered}
\vec{x}=\left\langle x_{1}, \ldots, x_{n}\right\rangle, \text { and } \\
Q^{\prime}=\exists \vec{x} \cdot\left(\phi(\vec{x}) \wedge x_{1}=c_{1} \ldots \wedge x_{n}=c_{n}\right)
\end{gathered}
$$

## From QNE to BQE

Assume a database $D$, a domain calculus query $Q=\{\vec{x} \mid \phi(x)\}$. Then $Q(D) \neq \emptyset$ iff $\exists \vec{x} \cdot \phi(\vec{x})$ evaluates to true in $D$.

From BQE to QNE and QOT $\rightsquigarrow$ trivial.

## Complexity Measures for BQE

## Combined complexity

The complexity of BQE without any assumptions about the input query $Q$ and database $D$ is called the combined complexity of BQE.

Further measures are obtained by restricting the input:

## Data and query complexity

Data complexity of BQE refers to the following decision problem:
Let $Q$ be some fixed Boolean query.
INSTANCE: An input database $D$.
QUESTION: Does $Q$ evaluate to true in $D$ ?

Query complexity of BQE refers to the following decision problem:
Let $D$ be some fixed input database.
INSTANCE: A Boolean query $Q$.
QUESTION: Does $Q$ evaluate to true in $D$ ?

## Relevant Complexity Classes

We recall the inclusions between some fundamental complexity classes:

$$
\mathrm{L} \subseteq \mathrm{P} \subseteq \mathrm{NP} \subseteq \mathrm{PSPACE} \subseteq \mathrm{EXPTIME}
$$

■ L is the class of all problems solvable in logarithmic space,
■ P -,, $-\quad$ in polynomial time,
■ NP -,, — in nondeterministic polynomial time,
■ PSPACE -,,- in polynomial space,
■ EXPTIME -,, - in exponential time.

## Complexity of First-order Queries

## Theorem (A)

The query complexity and the combined complexity of domain calculus queries is PSPACE-complete (even if we disallow negation and equality atoms). The data complexity is in L (actually, even in a much lower class).

To prove the theorem, we proceed in steps as follows:
1 We provide an algorithm for query evaluation:

- it shows PSPACE membership for combined complexity (and thus for query complexity as well), and
- L membership w.r.t. data complexity,

2 We show PSPACE-hardness of query complexity (clearly, the lower bound applies for combined complexity as well).

## An algorithm for query evaluation

- We consider an arbitrary FO formula $\psi$ and a database $D$.

■ W.l.o.g., the formula is of the form

$$
\psi=\exists x_{1} \forall y_{1} \ldots \exists x_{n} \forall y_{n} \varphi\left(x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right) .
$$

■ Let the active domain dom of $D$ be dom $=\left\{a_{1}, \ldots, a_{m}\right\}$.
■ For the evaluation of the formula, we design two procedures evaluate $_{\exists}$ and evaluate ${ }_{\theta}$, which call each other recursively.
■ The algorithm uses global variables $n$ and $X=\left\{x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right\}$.

## GLOBAL $x_{1}, y_{1}, \ldots, x_{n}, y_{n}$

## Boolean evaluate $_{\exists}$ (Integer $i$ )

for $x_{i}$ from $a_{1}$ to $a_{m}$ do
if evaluate $\forall_{\forall}(i)=$ true then return true
endfor
return false.
Boolean evaluate $_{\forall}($ Integer $i)$
for $y_{i}$ from $a_{1}$ to $a_{m}$ do
if $i=n$ then
if $\varphi$ evaluates to false under the current values of $x_{1}, y_{1}, \ldots, x_{n}, y_{n}$ then return false endif
else
if evaluate $_{\exists}(i+1)=$ false then return false
endif
endfor
return true.

By construction: $\psi$ is true in $D$ iff evaluate ${ }_{\exists}(1)=$ true.

Let's analyze the space usage of our algorithm. We have to store:
1 The input database $D$ and the formula $\psi$ :

- do not contribute to the space requirements.

2 The global variables $X=\left\{x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right\}$.

- Each variable requires $\mathcal{O}(\log m)$ bits of space. Thus $X$ needs $\mathcal{O}(n \log m)$ bits. Note that $X$ requires logarithmic space if $\psi$ is fixed.
3 A call stack $\mathcal{S}=\left\langle S_{1}, \ldots, S_{k}\right\rangle$, where $k \leq 2 n$ and each $S_{j}$ stores a state in which a subroutine is called. Clearly, for both subroutines a state $S_{j}$ only needs to store the value of $i$ and the return position in the subroutine.
- Storing a value $i \in\{1, \ldots, 2 n\}$ requires logarithmic space in the size of $\psi$ (i.e. $\mathcal{O}(\log n)$ ), but only constant space if $\psi$ is fixed. (The return position requires constant space in both cases.)
- Hence $\mathcal{S}$ needs $\mathcal{O}(n \log n)$ bits of storage, which is constant if $\psi$ is fixed.

4 Space for evaluating $\varphi$ in an assignment

- requires a transversal of the parse tree of $\psi$ : space $\mathcal{O}(\log \|\psi\|)$ suffices.

Overall we need $\mathcal{O}(n \log m+n \log n+\log \|\psi\|)$ bits of storage.
$\mathcal{O}(n \log m+n \log n+\log \|\psi\|)$ means that we only need polynomial space in the combined size of $D$ and $\psi$.

## Proposition

BQE $\in$ PSPACE w.r.t. combined complexity. This also implies BQE $\in$ PSPACE w.r.t. query complexity.

If $\psi$ is fixed, then the space required is $\mathcal{O}(\log m)$, i.e. logarithmic in data.

## Proposition

$\mathbf{B Q E} \in \mathrm{L}$ w.r.t. data complexity.

NOTE: Note that $\mathrm{L} \subseteq P$. In fact, one can show completeness of BQE w.r.t. data complexity for a much lower circuit class $A C_{0} \subseteq L$.

## The PSPACE lower bound

To prove the PSPACE-hardness result, we first recall quantified Boolean formulae:

## QSAT (QBF)

INSTANCE: An expression $\exists x_{1} \forall x_{2} \exists x_{3} \cdots Q x_{n} \phi$, where $Q$ is either $\forall$ or $\exists$ and $\phi$ is a Boolean formula in CNF with variables from $\left\{x_{1}, x_{2}, x_{3}, \ldots, x_{n}\right\}$.
QUESTION: Is there a truth value for the variable $x_{1}$ such that for both truth values of $x_{2}$ there is a truth value for $x_{3}$ and so on up to $x_{n}$, such that $\phi$ is satisfied by the overall truth assignment?

## Theorem

QSAT is PSPACE-complete.
Remark. A detailed proof is given in the Komplexitätstheorie lecture.

## Proof of the PSPACE-Hardness of BQE

The PSPACE-hardness result for Theorem (A) can be shown by a reduction from the QSAT-problem. Let $\psi$ be an arbitrary QBF with

$$
\psi=\exists x_{1} \forall x_{2} \ldots Q x_{n} \alpha\left(x_{1}, \ldots, x_{n}\right)
$$

where $Q$ is either $\forall$ or $\exists$ and $\alpha$ is a quantifier-free Boolean formula with variables in $\left\{x_{1}, \ldots, x_{n}\right\}$.
We first define the (fixed) input database $D$ over the predicate symbols $\mathcal{L}=\{$ istrue, isequal, not, or, and $\}$ with the obvious meaning:
$D=\{$ istrue $(1)$, isequal $(0,0)$, isequal $(1,1), \operatorname{not}(1,0), \operatorname{not}(0,1)$,
$\operatorname{or}(1,1,1)$, or $(1,0,1)$, or $(0,1,1)$, or $(0,0,0)$, and $(1,1,1)$, and $(1,0,0)$, and $(0,1,0)$, and $(0,0,0)\}$

## Proof of the PSPACE-Hardness (continued)

For each sub-formula $\beta$ of $\alpha$, we define a quantifier-free, first-order formula $T_{\beta}\left(z_{1}, \ldots, z_{n}, x\right)$ with the following intended meaning: if the variables $x_{i}$ have the truth value $z_{i}$, then the formula $\beta\left(x_{1}, \ldots, x_{n}\right)$ evaluates to the truth value $x$.
The formulae $T_{\beta}\left(z_{1}, \ldots, z_{n}, x\right)$ can be defined inductively w.r.t. the structure of $\alpha$ as follows:
Case $\beta=$

$$
\begin{array}{ll}
x_{i}(\text { with } 1 \leq i \leq n): \quad & T_{\beta}(\bar{z}, x) \equiv \text { isequal }\left(z_{i}, x\right) \\
\neg \beta^{\prime}: & T_{\beta}(\bar{z}, x) \equiv \exists t_{1} T_{\beta^{\prime}}\left(\bar{z}, t_{1}\right) \wedge \operatorname{not}\left(t_{1}, x\right) \\
\beta_{1} \wedge \beta_{2}: & T_{\beta}(\bar{z}, x) \equiv \exists t_{1}, t_{2} T_{\beta_{1}}\left(\bar{z}, t_{1}\right) \wedge T_{\beta_{2}}\left(\bar{z}, t_{2}\right) \wedge \operatorname{and}\left(t_{1}, t_{2}, x\right) \\
\beta_{1} \vee \beta_{2}: & T_{\beta}(\bar{z}, x) \equiv \exists t_{1}, t_{2} T_{\beta_{1}}\left(\bar{z}, t_{1}\right) \wedge T_{\beta_{2}}\left(\bar{z}, t_{2}\right) \wedge \operatorname{or}\left(t_{1}, t_{2}, x\right)
\end{array}
$$

## Proof of the PSPACE-Hardness (continued)

The first-order query $\phi$ is then defined as follows:

$$
\phi \equiv \exists x \exists z_{1} \forall z_{2} \ldots Q z_{n} T_{\alpha}(\bar{z}, x) \wedge \text { istrue }(x)
$$

where $Q$ is either $\forall$ or $\exists$ (as in the formula $\psi$ ).
We claim that this problem reduction is correct, i.e.:
The QBF $\psi=\exists x_{1} \forall x_{2} \ldots Q x_{n} \alpha\left(x_{1}, \ldots, x_{n}\right)$ is true $\Leftrightarrow$ the first-order query $\phi \equiv \exists x \exists z_{1} \forall z_{2} \ldots Q z_{n} T_{\alpha}(\bar{z}, x) \wedge$ istrue $(x)$ evaluates to true over the database $D$.
The proof is straightforward. It suffices to show by induction on the structure of $\alpha$ that the formulae $T_{\beta}\left(z_{1}, \ldots, z_{n}, x\right)$ indeed have the intended meaning.

## Complexity of Conjunctive Queries

Recall that conjunctive queries (CQs) are a special case of first-order queries whose only connective is $\wedge$ and whose only quantifier is $\exists$ (i.e., $\vee$, $\neg$ and $\forall$ are excluded).

$$
\text { E.g.: } \quad Q=\{\langle x\rangle \mid \exists y, z \cdot R(x, y) \wedge R(y, z) \wedge P(z, x)\}
$$

## Theorem (B)

The query complexity and the combined complexity of BQE for conjunctive queries is NP-complete.

## Proof

NP-Membership (of the combined complexity). For each variable $u$ of the query, we guess a domain element to which $u$ is instantiated. Then we check whether all the resulting ground atoms in the query body exist in $D$. This check is obviously feasible in polynomial time.

## Proof (continued)

Hardness (of the query complexity). We reduce the NP-complete 3-SAT problem to our problem. For this purpose, we consider the following input database (over a ternary relation symbol $c$ and a binary relation symbol $v$ ) as fixed:

$$
\begin{aligned}
D=\{ & c(1,1,1), c(1,1,0), c(1,0,1), c(1,0,0) \\
& c(0,1,1), c(0,1,0), c(0,0,1), v(1,0), v(0,1)\}
\end{aligned}
$$

Now let an arbitrary instance of the 3-SAT problem be given through the 3-CNF formula $\Phi=\bigwedge_{i=1}^{n} l_{i 1} \vee l_{i 2} \vee l_{i 3}$ over the propositional variables $x_{1}, \ldots, x_{k}$. Then we define a conjunctive query $Q$ as follows:
$\left(\exists x_{1}, \ldots, x_{k}\right) c\left(l_{11}^{*}, l_{12}^{*}, l_{13}^{*}\right) \wedge \ldots \wedge c\left(l_{n 1}^{*}, l_{n 2}^{*}, l_{n 3}^{*}\right) \wedge v\left(x_{1}, \bar{x}_{1}\right) \wedge \cdots \wedge v\left(x_{k}, \bar{x}_{k}\right)$
where $I^{*}=x$ if $I=x$, and $I^{*}=\bar{x}$ if $I=\neg x$. Moreover, $\bar{x}_{1}, \ldots, \bar{x}_{k}$ are fresh first-order variables. By slight abuse of notation, we thus use $x_{i}$ to denote either a propositional atom (in $\Phi$ ) or a first-order variable (in $Q$ ). It is straightforward to verify that the 3-CNF formula $\Phi$ is satisfiable $\Leftrightarrow$ $Q$ evaluates to true in $D$.

## Complexity of Datalog

## Theorem (C)

Query evaluation in Datalog has the following complexity:
■ P-complete w.r.t. data complexity, and
■ EXPTIME-complete w.r.t combined and query complexity.
To prove the theorem, we first concentrate on ground Datalog programs:

- A program is ground if it has no variables.
- Such programs are also known as propositional logic programs.

■ Note that a ground atom $R($ tim, bob) can be seen as a propositional variable $R_{\text {tim, bob }}$.

## Ground Datalog

## Theorem

Query evaluation for ground Datalog programs is P-complete w.r.t. combined complexity.

## Proof: (Membership)

- Recall that the semantics of a given program $P$ can be defined as the least fixed-point of the immediate consequence operator $T_{P}$
■ This least fixpoint $T_{P}^{\omega}(D B)$ can be computed in polynomial time even if the "naive" evaluation algorithm is applied.
- The number of iterations (i.e. applications of $T_{P}$ ) is bounded by the number of rules plus 1.
- Each iteration step is clearly feasible in polynomial time.


## P-hardness of Ground Datalog

## Proof: (Hardness)

■ By encoding of a TM. Assume $M=\left(K, \Sigma, \delta, q_{s t a r t}\right)$, an input string $I$ and a number of steps $N$, where $N$ is a polynomial of $|I|$.

- We construct in logspace a program $P(M, N)$, a database $D B(I, N)$ and an atom $A$ such that

$$
A \in T_{P(M, N)}^{\omega}(D B(I, N)) \text { iff } M \text { accepts } I \text { in } N \text { steps. }
$$

- Recall that the transition function $\delta$ of $M$ with a single tape can be represented by a table whose rows are tuples $t=\left\langle q_{1}, \sigma_{1}, q_{2}, \sigma_{2}, d\right\rangle$. Such a tuple $t$ expresses the following if-then-rule:
if at some time instant $\tau$ the machine is in state $q_{1}$, the cursor points to cell number $\pi$, and this cell contains symbol $\sigma_{1}$ then at instant $\tau+1$ the machine is in state $q_{2}$, cell number $\pi$ contains symbol $\sigma_{2}$, and the cursor points to cell number $\pi+d$.


## P-hardness of Ground Datalog: the Atoms

The propositional atoms in $P(M, N)$.
(there are many, but only polynomially many...)
symbol $_{\alpha}[\tau, \pi]$ for $0 \leq \tau \leq N, 0 \leq \pi \leq N$ and $\alpha \in \Sigma$. Intuitive meaning: at instant $\tau$ of the computation, cell number $\pi$ contains symbol $\alpha$.
$\operatorname{cursor}[\tau, \pi]$ for $0 \leq \tau \leq N$ and $0 \leq \pi \leq N$. Intuitive meaning: at instant $\tau$, the cursor points to cell number $\pi$.
$\operatorname{state}_{q}[\tau]$ for $0 \leq \tau \leq N$ and $q \in K$. Intuitive meaning: at instant $\tau$, the machine $M$ is in state $q$.
accept Intuitive meaning: $M$ has reached state $q_{\text {yes }}$.

## P-hardness of Ground Datalog: the Database

The construction of the database $D B(I, N)$ :

$$
\begin{array}{ll}
\text { symbol }_{\triangleright}[0,0], & \\
\text { symbol }_{\sigma}[0, \pi], & \text { for } 0<\pi \leq|I|, \text { where } I_{\pi}=\sigma \\
\text { symbol }_{\cup}[0, \pi], & \text { for }|I| \leq \pi \leq N \\
\text { cursor }[0,0], & \\
\text { state }_{q_{\text {start }}[0] .} &
\end{array}
$$

## P-hardness of Ground Datalog: the Rules

■ transition rules: for each entry $\left\langle q_{1}, \sigma_{1}, q_{2}, \sigma_{2}, d\right\rangle, 0 \leq \tau<N$, $0 \leq \pi<N$, and $0 \leq \pi+d$.

$$
\begin{aligned}
& \text { symbol }_{\sigma_{2}}[\tau+1, \pi] \leftarrow \text { state }_{q_{1}}[\tau] \text {, symbol }{ }_{\sigma_{1}}[\tau, \pi] \text {, cursor }[\tau, \pi] \\
& \text { cursor }[\tau+1, \pi+d] \leftarrow \text { state }_{q_{1}}[\tau] \text {, symbol }{ }_{\sigma_{1}}[\tau, \pi] \text {, cursor }[\tau, \pi] \\
& \text { state }_{q_{2}}[\tau+1] \leftarrow \operatorname{state}_{q_{1}}[\tau], \text { symbol }_{\sigma_{1}}[\tau, \pi], \text { cursor }[\tau, \pi]
\end{aligned}
$$

■ inertia rules: where $0 \leq \tau<N, 0 \leq \pi<\pi^{\prime} \leq N$

$$
\begin{array}{rc}
\text { symbol }_{\sigma_{1}}[\tau+1, \pi] & \leftarrow \text { symbol }_{\sigma_{1}}[\tau, \pi], \text { cursor }\left[\tau, \pi^{\prime}\right] \\
\text { symbol }_{\sigma_{1}}\left[\tau+1, \pi^{\prime}\right] & \leftarrow \text { symbol }_{\sigma_{1}}\left[\tau, \pi^{\prime}\right], \text { cursor }[\tau, \pi]
\end{array}
$$

- accept rules: for $0 \leq \tau \leq N$

$$
\text { accept } \leftarrow \text { state }_{q_{\mathrm{yes}}}[\tau]
$$

## P-hardness of Ground Datalog

■ The encoding precisely simulates the behaviour of $M$ on input I up to $N$ steps. (This can be formally shown by induction on the time steps.)

- accept $\in T_{P(M, N)}^{\omega}(D B(I, N))$ iff $M$ accepts $I$ in $N$ steps.
- The construction is feasible in logarithmic space.
- Note that each rule in $P(M, N)$ has at most 4 atoms. In fact, P-hardness applies already for programs with at most 3 atoms in the rules:
- Simply replace each $A \leftarrow B, C, D$ in $P(M, N)$ by $A \leftarrow B, E$ and $E \leftarrow C, D$, where $E$ is a fresh atom.


## Data Complexity of Datalog

## Proposition

Query evaluation in Datalog is P -complete w.r.t. data complextity.

## Proof: (Membership)

Effective reduction to reasoning over ground Datalog programs is possible. Given a program $P$, a database $D B$, and atom $A$ :

■ Generate $P^{\prime}=\operatorname{ground}(P, D B)$, i.e. the set all ground instances of rules in $P$ :

$$
\operatorname{ground}(P, D B)=\bigcup_{r \in P} \operatorname{Ground}(r ; P, D B)
$$

NB: more details on Ground $(r ; P, D B)$ in Lecture 2.

- Decide whether $A \in T_{P^{\prime}}^{\omega}(D B)$.


## Grounding Complexity

Given a program $P$ and a database $D B$, the number of rules in ground $(P, D B)$ is bounded by

$$
|P| * \# \operatorname{consts}(P, D B)^{v \max }
$$

- vmax is the maximum number of different variables in any rule $r \in P$

■ \#consts $(P, D B)$ is the number of constants occurring in $P$ and $D B$.

- $\operatorname{ground}(P, D B)$ is polynomial in the size of $D B$.
- Hence, the complexity of propositional logic programming is an upper bound for the data complexity.

■ Note that ground $(P, D B)$ can be exponential in the size of $P$.

## Data Complexity of Datalog: P-hardness

## Proof: Hardness

The P-hardness can be shown by writing a simple Datalog meta-interpreter for ground programs with at most 3 atoms per rule:

■ Represent rules $A_{0} \leftarrow A_{1}, \ldots, A_{i}$ of such a program $P$, where $0 \leq i \leq 2$, using database facts $\left\langle A_{0}, \ldots, A_{i}\right\rangle$ in an $(i+1)$-ary relation $R_{i}$ on the propositional atoms.
■ Then, the program $P$ which is stored this way in a database $D B_{M I}(P)$ can be evaluated by a fixed Datalog program $P_{M I}$ which contains for each relation $R_{i}, 0 \leq i \leq k$, a rule

$$
T\left(X_{0}\right) \leftarrow T\left(X_{1}\right), \ldots, T\left(X_{i}\right), R_{i}\left(X_{0}, \ldots, X_{i}\right)
$$

- $T(x)$ intuitively means that atom $x$ is true. Then,

$$
A \in T_{P}^{\omega}(D B) \text { iff } T(A) \in T_{P_{M 1}}^{\omega}\left(D B_{M I}(P)\right)
$$

- P-hardness of the data complexity of Datalog is then immediately obtained.


## Combined and Query Complexity of Datalog

## Proposition

Datalog is EXPTIME-complete w.r.t. query and combined complexity.

## Proof

(Membership) Grounding $P$ using $D B$ leads to a propositional program ground $(P, D B)$ whose size is exponential in the size of $P$ and $D B$. Hence, the query and the combined complexity is in EXPTIME.
(Hardness) We show hardness for query complexity only. Goal: adapt our previous encoding of TM $M$ and input $/$ to obtain a program $P_{\text {dat }}(M, I, N)$ and a fixed database $D B_{d a t}$ to decide acceptance of $M$ on I within $N=2^{m}$ steps, where $m=n^{k}(n=|I|)$ is a polynomial.
Note: We are not allowed to generate an exponentially large program by using exponentially many propositional atoms (the reduction would not be polynomial!!).
More details next...

## Query Complexity of Datalog: EXPTIME-hardness

Ideas for lifting $P(M, N)$ and $D B(I, N)$ to $P_{d a t}(M, I, N)$ and $D B_{d a t}$ :
$■$ use the predicates $\operatorname{symbol}_{\sigma}(\mathbf{X}, \mathbf{Y}), \operatorname{cursor}(\mathbf{X}, \mathbf{Y})$ and $\operatorname{state}_{s}(\mathbf{X})$ instead of the propositional letters symbol ${ }_{\sigma}[X, Y]$, cursor $[X, Y]$ and state $_{q}[X]$ respectively.

- W.I.o.g., let $N$ be of the form $N=2^{m}-1$ for some integer $m \geq 1$. The time points $\tau$ and tape positions $\pi$ from 0 to $N$ are encoded in binary, i.e. by $m$-ary tuples $t_{\tau}=\left\langle c_{1}, \ldots, c_{m}\right\rangle, c_{i} \in\{0,1\}$, $i=1, \ldots, m$, such that $0=\langle 0, \ldots, 0\rangle, 1=\langle 0, \ldots, 1\rangle$, $N=\langle 1, \ldots, 1\rangle$.
- The functions $\tau+1$ and $\pi+d$ are realized by means of the successor Succ ${ }^{m}$ from a linear order $\leq^{m}$ on $\{0,1\}^{m}$.


## Query Complexity of Datalog: EXPTIME-hardness

The predicates Succ ${ }^{m}$, First $^{m}$, and Last ${ }^{m}$ are provided.

- The database facts symbol ${ }_{\sigma}[0, \pi]$ are readily translated into the Datalog rules

$$
\text { symbol }_{\sigma}(\mathbf{X}, \mathbf{t}) \leftarrow \text { First }^{m}(\mathbf{X})
$$

where $\mathbf{t}$ represents the position $\pi$,
■ Similarly for the facts cursor $[0,0]$ and state $_{s_{0}}[0]$.
■ Database facts symbol $[0, \pi]$, where $|I| \leq \pi \leq N$, are translated to the rule

$$
\text { symbol }_{\mathrm{U}}(\mathbf{X}, \mathbf{Y}) \leftarrow \text { First }^{m}(\mathbf{X}), \leq^{m}(\mathbf{t}, \mathbf{Y})
$$

where $\mathbf{t}$ represents the number $|I|$.

## Query Complexity of Datalog: EXPTIME-hardness

- Transition and inertia rules: for realizing $\tau+1$ and $\pi+d$, use in the body atoms $\operatorname{Succ}^{m}\left(\mathbf{X}, \mathbf{X}^{\prime}\right)$. For example, the clause

$$
\text { symbol }_{\sigma_{2}}[\tau+1, \pi] \leftarrow \text { state }_{q_{1}}[\tau], \text { symbol }_{\sigma_{1}}[\tau, \pi], \text { cursor }[\tau, \pi]
$$

is translated into
$\operatorname{symbol}_{\sigma_{2}}\left(\mathbf{X}^{\prime}, \mathbf{Y}\right) \leftarrow \operatorname{state}_{q_{1}}(\mathbf{X}), \operatorname{symbol}_{\sigma_{1}}(\mathbf{X}, \mathbf{Y}), \operatorname{cursor}(\mathbf{X}, \mathbf{Y}), \operatorname{Succ}^{m}\left(\mathbf{X}, \mathbf{X}^{\prime}\right)$.

- The translation of the accept rules is straightforward.


## Defining $\operatorname{Succ}^{m}\left(\mathbf{X}, \mathbf{X}^{\prime}\right)$ and $\leq^{m}$

- The ground facts $\operatorname{Succ}^{1}(0,1), \operatorname{First}^{1}(0)$, and $\operatorname{Last}^{1}(1)$ are provided in $D B_{d a t}$.
- For an inductive definition, suppose $\operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}), \operatorname{First}^{i}(\mathbf{X})$, and Last $^{i}(\mathbf{X})$ tell the successor, the first, and the last element from a linear order $\leq^{i}$ on $\{0,1\}^{i}$, where $\mathbf{X}$ and $\mathbf{Y}$ have arity $i$. Then, use rules

$$
\begin{aligned}
& \operatorname{Succ}^{i+1}(Z, \mathbf{X}, Z, \mathbf{Y}) \leftarrow \operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}) \\
& \operatorname{Succ}^{i+1}\left(Z, \mathbf{X}, Z^{\prime}, \mathbf{Y}\right) \leftarrow \operatorname{Succ}^{1}\left(Z, Z^{\prime}\right), \operatorname{Last}^{i}(\mathbf{X}), \operatorname{First}^{i}(\mathbf{Y}) \\
& \operatorname{First}^{+1}(Z, \mathbf{X}) \leftarrow \\
& \operatorname{Lirst}^{(1+1}(Z), \operatorname{First}^{i}(\mathbf{X}) \\
& \operatorname{Last}^{+1}(Z) \leftarrow \operatorname{Last}^{1}(Z), \operatorname{Last}^{( }(\mathbf{X})
\end{aligned}
$$

## Defining $\operatorname{Succ}^{m}\left(\mathbf{X}, \mathbf{X}^{\prime}\right)$ and $\leq^{m}$

- The ground facts $\operatorname{Succ}^{1}(0,1)$, $\operatorname{First}^{1}(0)$, and $\operatorname{Last}^{1}(1)$ are provided in $D B_{d a t}$.
- For an inductive definition, suppose $\operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y})$, First $^{i}(\mathbf{X})$, and Last $^{i}(\mathbf{X})$ tell the successor, the first, and the last element from a linear order $\leq^{i}$ on $\{0,1\}^{i}$, where $\mathbf{X}$ and $\mathbf{Y}$ have arity $i$. Then, use rules

$$
\begin{aligned}
\operatorname{Succ}^{i+1}(0, \mathbf{X}, 0, \mathbf{Y}) & \leftarrow \operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}) \\
\operatorname{Succ}^{i+1}(1, \mathbf{X}, 1, \mathbf{Y}) & \leftarrow \operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}) \\
\operatorname{Succ}^{i+1}(0, \mathbf{X}, 1, \mathbf{Y}) & \leftarrow \operatorname{Last}^{i}(\mathbf{X}), \operatorname{First}^{i}(\mathbf{Y}) \\
\operatorname{First}^{i+1}(0, \mathbf{X}) & \leftarrow \operatorname{First}^{i}(\mathbf{X}) \\
\operatorname{Last}^{i+1}(1, \mathbf{X}) & \leftarrow \operatorname{Last}^{i}(\mathbf{X})
\end{aligned}
$$

## Defining $\operatorname{Succ}^{m}\left(\mathbf{X}, \mathbf{X}^{\prime}\right)$ and $\leq^{m}$

- The ground facts $\operatorname{Succ}^{1}(0,1)$, First $^{1}(0)$, and $\operatorname{Last}^{1}(1)$ are provided in $D B_{\text {dat }}$.
■ For an inductive definition, suppose $\operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}), \operatorname{First}^{i}(\mathbf{X})$, and Last $^{i}(\mathbf{X})$ tell the successor, the first, and the last element from a linear order $\leq^{i}$ on $\{0,1\}^{i}$, where $\mathbf{X}$ and $\mathbf{Y}$ have arity $i$. Then, use rules

$$
\begin{aligned}
\operatorname{Succ}^{i+1}(0, \mathbf{X}, 0, \mathbf{Y}) & \leftarrow \operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}) \\
\operatorname{Succ}^{i+1}(1, \mathbf{X}, 1, \mathbf{Y}) & \leftarrow \operatorname{Succ}^{i}(\mathbf{X}, \mathbf{Y}) \\
\operatorname{Succ}^{i+1}(0, \mathbf{X}, 1, \mathbf{Y}) & \leftarrow \operatorname{Last}^{i}(\mathbf{X}), \operatorname{First}^{i}(\mathbf{Y}) \\
\operatorname{First}^{i+1}(0, \mathbf{X}) & \leftarrow \operatorname{First}^{i}(\mathbf{X}) \\
\operatorname{Last}^{i+1}(1, \mathbf{X}) & \leftarrow \operatorname{Last}^{i}(\mathbf{X})
\end{aligned}
$$

- The order $\leq^{m}$ is easily defined from Succ ${ }^{m}$ by two clauses

$$
\begin{aligned}
& \leq^{m}(\mathbf{X}, \mathbf{X}) \\
& \leq^{m}(\mathbf{X}, \mathbf{Y}) \\
& \leftarrow \\
& \operatorname{Succ}^{m}(\mathbf{X}, \mathbf{Z}), \leq^{m}(\mathbf{Z}, \mathbf{Y})
\end{aligned}
$$

## Combined and Query Complexity of Datalog: Conclusion

■ Let $L$ be an arbitrary language in EXPTIME, i.e., there exists a Turing machine $M$ deciding $L$ in exponential time. Then there is a constant $k$ such that $M$ accepts/rejects every input $I$ within $2^{\left|/| |^{k}\right.}$ steps.

- The program $P_{d a t}\left(M, I,|I|^{k}\right)$ is constructible from $M$ and $I$ in polynomial time (in fact, careful analysis shows feasibility in logarithmic space).
■ accept is in the answer of $P_{\text {dat }}\left(M, I,|I|^{k}\right)$ evaluated over $D B_{d a t} \Leftrightarrow$ $M$ accepts input $I$ within $N$ steps.
■ Thus the EXPTIME-hardness follows.


## Complexity of Datalog with Stratified Negation

## Theorem

Reasoning in stratified ground Datalog programs with negation is P-complete. Stratified Datalog with negation is

■ P-complete w.r.t. data complexity, and
■ EXPTIME-complete w.r.t combined and query complexity.

- A ground stratified program $P$ can be partitioned into disjoint sets $S_{1}, \ldots, S_{n}$ s.t. the semantics of $P$ is computed by successively computing in polynomial time the fixed-points of the immediate consequence operators $T_{S_{1}}, \ldots, T_{S_{n}}$.
- As with plain Datalog, for programs with variables, the grounding step causes an exponential blow-up.


## Learning Objectives

■ The BQE, QOT and QNE problems

- The notions of combined, data and query complexity
- The complexity of first-order queries
- The complexity of conjunctive queries
- The complexity of plain and stratified Datalog

